

Towards Localisation of Keywords in Speech using Weak Supervision

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Detection task



Utterance

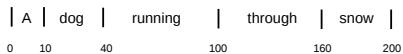
A dog running through snow

Transcription

Localisation task



Utterance



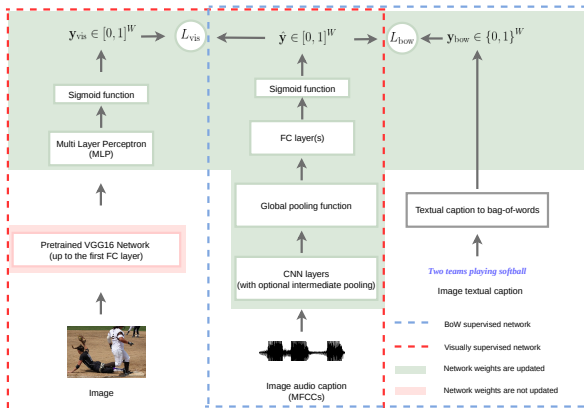
Frame-wise alignment
of transcription



Image



Utterance





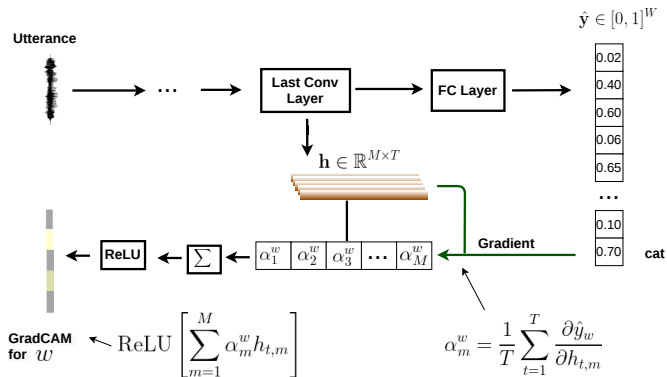
Two localisation methods:

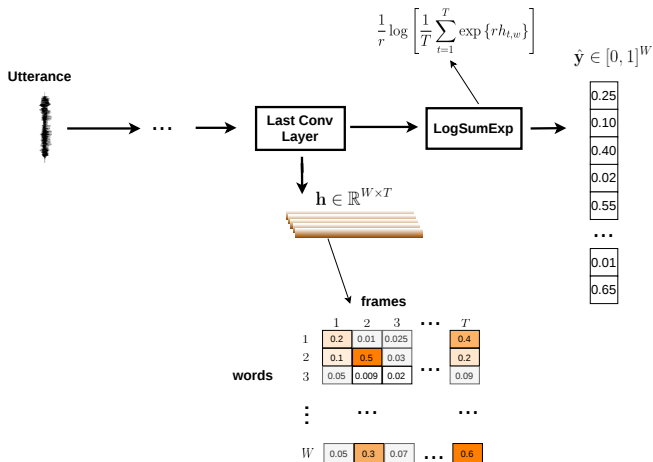
▶ GradCAM

- Introduced in the vision domain to localise an object in an image.
- Works with any **trained** CNN architecture.
- Determines the portion of an input that contributes to a decision of interest using gradient information.

▶ PSC

- Designed to simultaneously perform detection and localisation of keywords in speech utterance.
- The CNN architecture is restricted in some ways (*No intermediate max-pooling; no fully-connected layers; LogSumExp function as the global pooling function*).





| Mechanism | Supervision method | |
|----------------|--------------------|--------|
| | BoW | Visual |
| PSC | 63.6 | 19.1 |
| GradCAM | 17.8 | 16.0 |

Table 1: Oracle localisation accuracy (%) when assuming perfect detection.

| Mechanism | BoW | | | | Visually-supervised | | | |
|----------------|----------|----------|-----------|----------|---------------------|----------|-----------|----------|
| | <i>P</i> | <i>R</i> | <i>F1</i> | Accuracy | <i>P</i> | <i>R</i> | <i>F1</i> | Accuracy |
| PSC | 75.2 | 53.0 | 62.2 | 50.4 | 28.6 | 8.0 | 12.5 | 7.6 |
| GradCAM | 17.7 | 24.5 | 20.5 | 13.2 | 5.0 | 5.7 | 5.3 | 4.4 |

Table 2: Actual localisation precision, recall, *F1* and accuracy (%) when taking detection into account with a threshold of $\lambda = 0.4$.

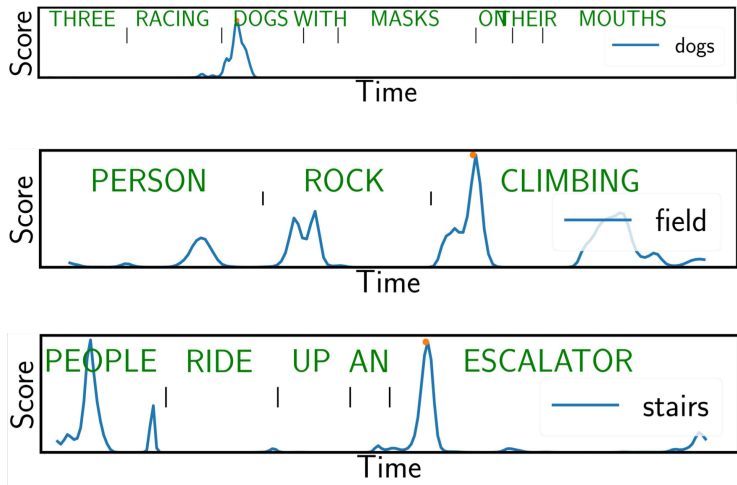


Figure 2: Examples of localisation with the visually supervised PSC mechanism. The keyword being localised is shown on the right of each plot.



- ▶ We asked whether keyword localisation in speech is possible with two forms of weak supervision when location information is not provided.
- ▶ We attempted to answer the question by comparing two localisation methods (PSC and GradCAM) with two forms of supervision: bag-of-word (BoW) labels and visual context.
- ▶ While the GradCAM (a saliency-based method) performed poorly, PSC (a method where localisation is performed as part of the network) performed well with BoW supervision and showed that visual supervision does provide potential for higher precision localisation.
- ▶ Our results suggests a mismatch between saliency-based localisation and the multi-label model used here, with a superior detection model performing poorly in localisation. This suggest that better localisation should be possible given a mechanism better aligned to the model and multi-label classification loss.

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16. Kamper, Herman, Aristotelis Anastassiou, and Karen Livescu. "Semantic query-by-example speech search using visual grounding." In Proc. ICASSP, 2019.
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Thank you for listening!

| Model | $\alpha = 0.4$ | | | $\alpha = 0.6$ | | |
|----------------------------|----------------|----------|-----------|----------------|----------|-----------|
| | <i>P</i> | <i>R</i> | <i>F1</i> | <i>P</i> | <i>R</i> | <i>F1</i> |
| <i>Visual supervision:</i> | | | | | | |
| PSC | 44.5 | 9.8 | 16.1 | 74.7 | 4.3 | 8.1 |
| GradCAM | 29.3 | 22.0 | 25.1 | 42.7 | 12.7 | 19.6 |
| <i>BoW supervision:</i> | | | | | | |
| PSC | 82.2 | 49.0 | 61.4 | 87.8 | 46.1 | 60.4 |
| GradCAM | 79.3 | 52.6 | 63.2 | 82.5 | 50.9 | 63.0 |

Table 3: Keyword detection scores (without considering localisation) with threshold α .

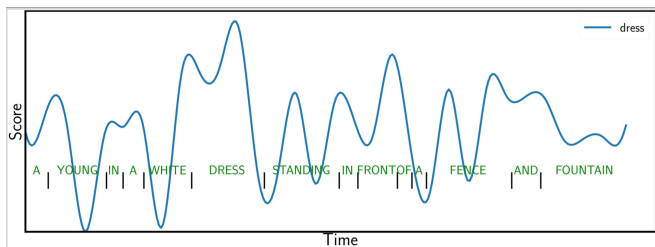


Figure 3: An example localisation with the GradCAM model for the keyword “dress”.